

#1.

4.30 For the LP given at the top of page 223 check whether $x = (7, 0, \frac{1}{2}, 0, 3, 0, \frac{1}{2})^T$ is an optimum feasible solution.

Exercises 223

$$\begin{aligned}
 \text{Maximize } z(x) &= x_1 + 2x_2 + x_3 - 3x_4 + x_5 + x_6 - x_7 \\
 \text{Subject to } & x_1 + x_2 - x_4 + 2x_6 - 2x_7 \leq 6 \\
 & x_2 - x_4 + x_5 - 2x_6 + 2x_7 \leq 4 \\
 & x_2 + x_3 + x_6 - x_7 \leq 2 \\
 & x_2 - x_4 - x_6 + x_7 \leq 1 \\
 & x_j \geq 0 \quad \text{for all } j
 \end{aligned}$$

#2

Minimize

$$z(x) = \sum_i \sum_j c_{ij} x_{ij}$$

Subject to

$$\sum_j x_{ij} = a_i \quad i = 1 \text{ to } m$$

$$\sum_i x_{ij} = b_j \quad j = 1 \text{ to } n \quad (4.10)$$

$$x_{ij} \geq 0 \quad \text{for all } i, j$$

4.31 For the transportation problem (4.10) with the following data, find an optimum feasible solution using the complementary slackness conditions, given that $u = (u_i) = (0, 3, -4)$, $v = (v_j) = (7, 2, -5, 7)$ is an optimum dual solution.

$$c = (c_{ij}) = \begin{pmatrix} 7 & 2 & -2 & 8 \\ 19 & 5 & -2 & 12 \\ 5 & 7.2 & -9 & 3 \end{pmatrix}$$

$$a = (a_i) = (3, 3, 4), \quad b = (b_j) = (2, 3, 2, 3)$$

#3

4.35 For the LP given below compute the primal and dual solutions associated with the basis corresponding to the basic vector (x_3, x_5, x_1) . Is it an optimum basis? Characterize the set of optimum solutions of this problem using the complementary slackness theorem. Do the same for the basic vector (x_5, x_2, x_3, x_8) for the LP given at the top of page 224.

x_1	x_2	x_3	x_4	x_5	x_6	x_7	$-z$	b
1	4	1	-2	2	5	1	0	11
0	-2	0	2	-1	-1	-1	0	-4
1	1	0	-1	1	3	2	0	4
2	7	1	-1	2	13	2	1	0

$x_j \geq 0$ for all j ; minimize z .

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4 Duality in Linear Programming

Minimize $3x_1 - 2x_2 + x_3 - x_4 - 5x_5 + 4x_6 - 2x_7 - 3x_8$
 Subject to $x_1 + x_2 + x_3 + x_4 + x_5 + x_6 + x_7 + x_8 = 14$
 $x_1 + x_2 + x_3 + x_5 + x_6 + x_7 = 9$
 $x_2 + x_2 + x_5 + x_6 = 5$
 $x_1 + x_5 = 2$
 $x_j \geq 0$ for all j

#4

4.14 Using Farkas' lemma, prove the following theorem of the alternative. If A is an $m \times n$

matrix and $b \in \mathbb{R}^m$, exactly one of the following two systems has a solution.

Either $Ax = b$ (I)

or $\pi A = 0 \quad \pi b = 1$ (II)